15 113 427/435.ccls. and (rotat\$3) USPAT; US	L Number	Hits	Search Text	DD	m:
115 427/435.ccls. and (rotat%6)					
115 427/435.ccls. and (rotats6)					2004/11/00 11:39
16					
115 427/435.ccls. and (rotat\$6)					
US-PGPUB; EPG, JPG DERMENT USBAT; USBA	16	115	427/435.ccls. and (rotat\$6)		2004/11/08 11:39
RFO; JFO; DERWENT USFAT;					
19				EPO; JPO;	
### Substrate ### 11				DERWENT	
19	17	6	427/435.ccls. and (rotat\$6) near3		2004/11/08 11:40
18			substrate	US-PGPUB;	
18				EPO; JPO;	
19 30 427/435.ccls. and cleaning adj solution US-PCPUB; EPO, JPO; DERMENT US-PCPUB; EPO, JPO; DERMENT US-PCPUB; EPO; JPO; DERMENT US-P	1.0	11	407/405	l	
19 30 427/435.ccls. and cleaning adj solution 19 19 20 427/435.ccls. and bath adj turnover 19 19 19 19 19 19 19 1	18	1 11	42//435.ccls. and (mov\$3) near3 substrate		2004/11/08 11:52
19 30 427/435.ccls. and cleaning adj solution DERMENT US-PGPUB; EDG; JPG; ERWENT US-PGPUB; EDG; JPG; DERWENT US-PGPUB; EDG; JPG; DEG; JPG; DEG; JPG; JPG; JPG; DEG; JPG; JPG; JPG; JPG; JPG; JPG; JPG; JP					
19			·		
20	19	30	127/125 colo and alcomina add activities		
20		30	427/433.0018. and cleaning adj solution	1	2004/11/08 13:39
20					
20				4	
21	20	2	427/435 ccls and bath adi turnover		2004/11/09 11.50
### 2004/11/04 11:59 ### 2004/11/08 11:59 ### 2004/11/05 13:34 ### 2004/11/05 13:34 ### 2004/11/05 13:34 ### 2004/11/04 13:53 ### 2004/11/04 13:53 ### 2004/11/04 13:53 ### 2004/11/04 13:55 ### 2004/11/04 13:55 ### 2004/11/04 13:56			12.7 130.0013. und bach daj curnover		2004/11/08 11:59
21	1				
21 0 427/436.ccls. and bath adj turnover USPAT; US-PGPUB; EPO; JPO; DERWENT US-PGFUB; EPO; JPO; DERWENT USPAT; US-PGFUB; EPO; JPO; DERWENT US-PGFUB; EPO; JPO; JPO; JPO; JPO; JPO; JPO; JPO; J			•		
US-PGPUB; EPO; JPO; DERMENT USPAT; US-PGPUB; EPO;	21	0	427/436.ccls, and bath add turnover	l .	2004/11/08 11.59
22 3 427/43\$.ccls. and bath adj turnover			au sum au sum au sum sum sum sum sum sum sum sum sum su	1	2004/11/00 11.59
22					
SPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB					
S24 articulat\$ near mechanical S25 S26 S27 S200 S20	22	3	427/43\$.ccls. and bath adj turnover		2004/11/08 11:59
DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT US-PGPUB; EPO; JPO; JPO; DERWENT US-PGPUB; EPO; JPO; DERWENT US-PGPUB; EPO; JPO; JPO; DERWENT US-PGPUB; LPO; JPO; JPO; JPO; JPO; JPO; JPO; JPO; J				1	
S24 articulat\$ near mechanical USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPU				EPO; JPO;	
S-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO;				DERWENT	
- 9 articulat\$ near electromechanical	_	524	articulat\$ near mechanical	USPAT;	2004/11/05 13:34
DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; U			,	US-PGPUB;	T .
Separaticulats near electromechanical USPAT; US-PGPUB; EPG; JPG; DERWENT USPAT; US				EPO; JPO;	
US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO;				1	
- 3549 (immers\$3 dip\$3) with (automat\$5)	-	9	articulats near electromechanical		2004/11/04 13:53
- 3549 (immers\$3 dip\$3) with (automat\$5) 3 ((immers\$3 dip\$3) with (automat\$5)) same electromechanical 4 ("4414350" "4994521" "5247863" "5061523" US-PGPUB; EPO; JPO; DERWENT USPAT; US				1	
3549					
3	_	3549	(immers\$3 dip\$3) with (automat\$5)	1	2004/11/04 14 16
Commers\$3 dip\$3) with (automat\$5)) same electromechanical Commers\$3 dip\$3) with (automat\$5)) same electromechanical Commers\$4 Commers\$5 Commers\$5 Commers\$6 Comm		0013	(Inductors dipro) with (adtomates)		2004/11/04 14:16
- 3 ((immers\$3 dip\$3) with (automat\$5)) same electromechanical USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US				1	
3					
electromechanical US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT US-PGPUB; EPO; JPO; DERWEN	- ,	3	((immers\$3 dip\$3) with (automat\$5)) same		2004/11/04 13:55
EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWEN				1	=====================================
- 11 ("4414350" "4994521" "5247863" "5061523" US-PGPUB; EPO; JPO; DERWENT USPAT; US-PG					
- 11 ("4414350" "4994521" "5247863" "5061523" USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT			•		
"5500460").pn. "5500460").pn. "4414350" "4994521" "5247863" "5061523" "5500460").pn. and immers\$3 "5500460").pn. and immers\$3 "22 articulat\$ near mechanical and immers\$ "1167 118/423.ccls. "118/423.ccls. and electromechanical "5500460").pn. and immers\$ "5061523" USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	- .	11	("4414350" "4994521" "5247863" "5061523"	1	2004/11/04 13:56
- ("4414350" "4994521" "5247863" "5061523" USPAT; USPAT; US-PGPUB; EPO; JPO; DERWENT U			"5500460").pn.		
- ("4414350" "4994521" "5247863" "5061523" USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; U					
"5500460").pn. and immers\$3 US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;		ا ۔ ا	/#4414050H #4004500H =======	The second secon	
EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; DERWENT USPAT; USPAT; USPAT; USPAT; US-PGPUB; EPO; DERWENT USPAT; USPAT; USPAT; USPAT; USPAT; USPAT; USPAT; USPAT; U	_	5	("4414350" "4994521" "5247863" "5061523"		2004/11/04 14:32
DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; DERWENT USPAT; USPAT; US-PGPUB; EPO; DERWENT USPAT; USPA			"5500460").pn. and immers\$3		
22 articulat\$ near mechanical and immers\$ USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; US-PGPUB; EPO; JPO; US-PGPUB; EPO; JPO;				1	
US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	_	22	articulats noar mochanical and demand		0004/11/01
EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;		~~	arcroutacy near mechanical and immers\$		2004/11/04 14:07
- 1167 118/423.ccls. DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; DERWENT USPAT; USPAT; US-PGPUB; EPO; DERWENT USPAT; USPA					
- 1167 118/423.ccls.					
4 118/423.ccls. and electromechanical USPAT; US-PGPUB; EPO; JPO; US-PGPUB; EPO; JPO; US-PGPUB; EPO; JPO; US-PGPUB; EPO; JPO;	_	1167	118/423.ccls.	1	2004/11/04 14:03
EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERUS PO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;		1107	==0, 120,0010,	'	2004/11/04 14:07
DERWENT USPAT; US-PGPUB; EPO; JPO;					
4 118/423.ccls. and electromechanical				l .	*
US-PGPUB; EPO; JPO;	·	4	118/423.ccls. and electromechanical	1	2004/11/04 14.09
EPO; JPO;					
	j				
			· · · · · · · · · · · · · · · · · · ·	1	

12	·	1	110/400		<u>. </u>
12	-	26	118/423.ccls. and robot		2004/11/04 14:15
12		i			
#4933119" "5337880" "5597609" "5679750" "5500600" "550150" "5570150" " "6008726" "601512" "6013718" NO. 6		10		1	
"5579756" "555066" "5750166" "6003316" No. 000236" "6051521" "6033716" No. 000236" "6051521" "6033716" No. 000236" "6051521" "6033716" No. 0004 14:13 2004/11/04 14:13 2004/11/04 14:14 2004/11/04 14:14 2004/11/04 14:15 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:16 2004/11/04 14:26 2004/11/04 200		12	("3956540" "4836960" "4900242" "4933119" "5337890" "5507600"	USPAT	2004/11/04 14:10
"6008256" "6015512" "6033718").PN.			"5679756" "5750060" "5750156"		
3			"6008296" "6015512" "6033718").PN.		
183	_	1		1	2004/11/04 14:13
Tobot\$5	_	_	(immers\$3 dip\$3) with (automat\$5) and	1	2004/11/04 14:14
136			robot\$5		2004/11/04 14:26
136 (immers\$3 dip\$3) with (automat\$5) and USPAT; robot					
Tobot	-	136	(immers\$3 dip\$3) with (automat\$5) and		2004/11/04 14-22
Table		•	robot	US-PGPUB;	2004/11/04 14.55
Topology Compare Com			·		
robot55	-	47	((immers\$3 dip\$3) with (automat\$5) and		2004/11/04 14-26
- 0			robot\$5) not ((immers\$3 dip\$3) with		2004/11/04 14:26
- 0			(automat\$5) and robot)		
"5500460").pn. and phenolic ("4414350" "4994521" "5247863" "5061523" "5500460").pn. and acid (coat\$3 layer\$3) with (automat\$5) with robot ("4414350" "4994521" "5247863" "5061523" "SPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US	_	0	("4414350" "4994521" "5247863" "5061523"	_	2004/11/04 14-20
Total			"5500460").pn. and phenolic		2004/11/04 14:32
Total				EPO; JPO;	
"5500460").pn. and acid "5500460").pn. and acid (coat\$3 layer\$3) with (automat\$5) with		7	("4414350" "4994521" "5247863" "5061523"	1	2004/11/04 14-22
Coat\$3 layer\$3) with (automat\$5) with DEPOKENT DE			"5500460").pn. and acid	US-PGPUB;	2004/11/04 14:33
Coat\$3 layer\$3) with (automat\$5) with robot USPAT; US-PGPUB; EPG; JPG; DERWENT USPAT; US-PGFUB; EPG; JPG; DERWENT USP					
Tobot	-	356	(coat\$3 layer\$3) with (automat\$5) with	_	2004/11/04 14-22
1			robot		2004/11/04 14:33
1	İ			•	
"5500460").pn. and dry adj film	_	1	("4414350" "4994521" "5247863" "5061523"		2004/11/04 14.41
- 2 6521687.pn. and phenolic USPAT; USPAT; USPGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB;			"5500460").pn. and dry adj film		2004/11/04 14:41
2 6521687.pn. and phenolic 2 6521687.pn. and phenolic 3 623/64.ccls. and (immers\$4 dip\$5) 2 700/245\$.ccls. and (immers\$4 dip\$5) 4 700/245\$.ccls. and (immers\$4 dip\$5) 4 827954.URPN. 4 827954.URPN. 5 1726 6 electromechanical near3 robot adj arm with (immers\$3 or dip\$4) 5 294 6 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 6 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 6 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 6 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 7 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 8 2004/11/04 15:24 2004/11/04 15:27 2004/11/04 15:28 2004/11/04 15:28 2004/11/04 15:28 2004/11/04 15:36 2004/11/04 15:36 2004/11/04 15:36 2004/11/04 15:36 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41 2004/11/04 15:41			·		
US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; J	_	2	6521687.pn. and phenolic	ſ	2004/11/04 15.24
DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT;					2004/11/04 13:24
3 623/64.ccls. and (immers\$4 dip\$5)			·		
US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; J	-	3	623/64.ccls. and (immers\$4 dip\$5)	1	2004/11/04 15:27
DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; U			, , , , , , , , , , , , , , , , , , , ,	US-PGPUB;	2004/11/04 15.27
- 25 700/245\$.ccls. and (immers\$4 dip\$5) - 6 901/14\$.ccls. and (immers\$4 dip\$5) - 7 4827954.URPN 1726 (immers\$4 dip\$5) near4 (robot\$3 automat\$3) - 0 electromechanical near3 robot adj arm with (immers\$3 or dip\$4) - 294 (electromechanical robot adj arm) with (immers\$3 or dip\$4) - 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls. - 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls.					
US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT USPAT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-P	-	25	700/245\$.ccls. and (immers\$4 dip\$5)		2004/11/04 15:28
- 0 electromechanical near3 robot adj arm with (immers\$3 or dip\$4) - 294 (electromechanical robot adj arm) with (immers\$3 or dip\$4) - 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) - 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) - 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls.			A 1 - 1	US-PGPUB;	-551,11,01 15.20
7 4827954.URPN. 1726 (immers\$4 dip\$5) near4 (robot\$3 automat\$3) USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO;					
US-PGPUB; EPO; JPO; DERWENT USPAT 2004/11/04 15:30 US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT	-	6	901/14\$.ccls. and (immers\$4 dip\$5)		2004/11/04 15:34
7 4827954.URPN. (immers\$4 dip\$5) near4 (robot\$3 automat\$3) 0 electromechanical near3 robot adj arm with (immers\$3 or dip\$4) 294 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4) 10 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls.			•	US-PGPUB;	13.54
7 4827954.URPN. (immers\$4 dip\$5) near4 (robot\$3 automat\$3) USPAT USPAT;					
1/26 (immers\$4 dip\$5) near4 (robot\$3 automat\$3) USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; (immers\$3 or dip\$4) USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-P	-	1 !			2004/11/04 15:30
electromechanical near3 robot adj arm with (immers\$3 or dip\$4) 294 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls. EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT U	_	1726	(immers\$4 dip\$5) near4 (robot\$3 automat\$3)	USPAT;	
- 294 (electromechanical robot adj arm with (immers\$3 or dip\$4) - 294 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls.				i	
electromechanical near3 robot adj arm with (immers\$3 or dip\$4) 294 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls.			•	, ,	
- 294 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls. EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	_	. 0	electromechanical near3 robot adj arm with	USPAT;	2004/11/04 15:41
- 294 (electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls. DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;			(Transcross of ATD\$4)	1	
0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4) 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls. 2004/11/04 15:41 USPAT; US-PGPUB; EPO; JPO; US-PGPUB; EPO; JPO;					
- 0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls. EPO; JPO; DERWENT USPAT; US-PGPUB; EPO; JPO;	_	294	(electromechanical robot adj arm) with	USPAT;	2004/11/04 15:41
O ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls. DERWENT USPAT; US-PGPUB; EPO; JPO;			(Inductors Of Gip\$4)		
0 ((electromechanical robot adj arm) with (immers\$3 or dip\$4)) and 118/423,50\$.ccls. US-PGPUB; EPO; JPO;				DERWENT	
EPO; JPO;	_	0	((electromechanical robot adj arm) with	USPAT;	2004/11/04 15:41
			(inductions of dipost)) and 118/423,50%.ccls.		
DERWENT				DERWENT	

-	9	1 (10200clomcomanical lobot da alim) willi	USPAT;	2004/11/04 15:41
		(immers\$3 or dip\$4)) and 118/\$.ccls.	US-PGPUB;	
1			EPO; JPO;	· j
_	3	mechanical near3 robot adj arm with	DERWENT	
		(immers\$3 or dip\$4)	USPAT;	2004/11/04 15:41
		(Induce1893 of dip94)	US-PGPUB;	
			EPO; JPO; DERWENT	
-	113	(mechanical robot adj arm) with (immers\$3	USPAT;	2004/11/04 15:54
		or dip\$4) and 118/\$.ccls.	US-PGPUB;	2004/11/04 15.54
			EPO; JPO;	
			DERWENT	
_	14	156/345.32.ccls. and (immers\$3 or dip\$4)	USPAT;	2004/11/04 15:55
			US-PGPUB;	,
			EPO; JPO;	
-	140	156/345.32.ccls.	DERWENT	0004/04/04 15
	110	1307343.32.0013.	USPAT; US-PGPUB;	2004/11/04 15:58
	1		EPO; JPO;	
			DERWENT	
-	39	427/43\$.ccls. and robot	USPAT;	2004/11/05 10:36
			US-PGPUB;	1 2001, 11, 00 10.50
1			EPO; JPO;	
	1100	407/405	DERWENT	
_	1100	427/435.ccls.	USPAT;	2004/11/05 10:37
			US-PGPUB;	
-			EPO; JPO;	
i –	138	427/435.ccls. and (autom\$6)	DERWENT USPAT;	2004/11/00 11 20
		127, 133. GGIB. and (aucomyo)	US-PGPUB;	2004/11/08 11:38
			EPO; JPO;	
			DERWENT	
-	60	427/435.ccls. and (automat\$6)	USPAT;	2004/11/05 10:41
			US-PGPUB;	
			EPO; JPO;	
		407/405	DERWENT	
_	6	427/435.ccls. and (electromechan\$3 robot\$3)	USPAT;	2004/11/08 11:39
	Ì	(LODOL\$3)	US-PGPUB;	1
			EPO; JPO;	
_	15	(electromechan\$3 robot\$3) with (dip\$3	DERWENT USPAT;	2004/11/05 11:48
		autodepos\$6 immer\$4) and (427/43\$.ccls.	US-PGPUB;	2004/11/05 11:48
		118/4\$.ccls.)	EPO; JPO;	
			DERWENT	
_	114	(electromechan\$3 robot\$3) and (dip\$3	USPAT;	2004/11/05 11:31
		autodepos\$6 immer\$4) and (427/43\$.ccls.	US-PGPUB;	
		118/4\$.ccls.)	EPO; JPO;	
_	82	(electromochans) mahatéal a l'il éa	DERWENT	
	02	(electromechan\$3 robot\$3) and (dip\$3 autodepos\$6 immer\$4) and (427/43\$.ccls.	USPAT;	2004/11/05 11:47
		118/4\$.ccls.) and (coat\$3)	US-PGPUB; EPO; JPO;	
			DERWENT	
-	1530	(electromechan\$3 robot\$3) and (dip\$3	USPAT;	2004/11/05 11:48
		autodepos\$6 immer\$4) and (vibrat\$6)	US-PGPUB;	
]			EPO; JPO;	
	_		DERWENT	
-	1	(electromechan\$3 robot\$3) with (dip\$3	USPAT;	2004/11/05 11:52
(·)		autodepos\$6 immer\$4) and (427/43\$.ccls.	US-PGPUB;	
		118/4\$.ccls.) and vibrat\$5	EPO; JPO;	[
_	36	(electromechan\$3 robot\$3) with (dip\$3	DERWENT	2004/11/05 12 22
		autodepos\$6 immer\$4) and drip\$5	USPAT; US-PGPUB;	2004/11/05 13:09
		-1,	EPO; JPO;	
			DERWENT	
-	536	(electromechan\$3 robot\$3) with (dip\$3	USPAT;	2004/11/05 13:02
,		autodepos\$6 immer\$4)	US-PGPUB;	
			EPO; JPO;	
_	22	(/=1	DERWENT	
	37	((electromechan\$3 robot\$3) with (dip\$3	USPAT;	2004/11/05 13:08
		<pre>autodepos\$6 immer\$4)) with (rotat\$3 spin\$3)</pre>	US-PGPUB;	
	Į	opinys,	EPO; JPO;	
			DERWENT	

_	93	two adj coat near3 adhesive	USPAT;	2004/11/05 13:09
			US-PGPUB;	1 1, 11, 00 13.03
			EPO; JPO;	
		·	DERWENT	
	37	(two adj coat near3 adhesive) and (dip\$3	USPAT;	2004/11/05 13:09
		autodepos\$6 immer\$4)	US-PGPUB;	= = = = = = = = = = = = = = = = = = =
			EPO; JPO;	
			DERWENT	
	127	427/435.ccls. and adhesive	USPAT;	2004/11/05 13:34
1			US-PGPUB;	2004/11/05 15.34
	İ		EPO; JPO;	-
		,	DERWENT	
-	21	427/43\$.ccls. and (prevent\$) near2 drip\$4	USPAT;	2004/11/05 13:42
		, , , , , , , , , , , , , , , , , , ,	US-PGPUB;	2004/11/05 15.42
		•	EPO; JPO;	
		·	DERWENT	
-	0	10609116.ap.	USPAT;	2004/11/05 14:02
		·	US-PGPUB;	2001/11/05 14.02
·	•		EPO; JPO;	
			DERWENT	·
-, 5	7	kucera.in. and mowrey.in.	USPAT;	2004/11/05 13:43
1		-	US-PGPUB;	2001/11/03 15:45
		•	EPO; JPO;	
			DERWENT	İ
- ,	8	(kucera.in. mowrey.in. cowles.in.) and	USPAT:	2004/11/05 14:08
		(autodeposition) and (adhesive)	US-PGPUB:	
			EPO; JPO;	
			DERWENT	
-	4	(kucera.in. mowrey.in. cowles.in.) and	USPAT;	2004/11/05 13:44
[(autodeposition) and (adhesive) and	US-PGPUB;	
		autom\$6	EPO; JPO;	
\			DERWENT	
	1	2000-532680.NRAN.	DERWENT	2004/11/05 14:09